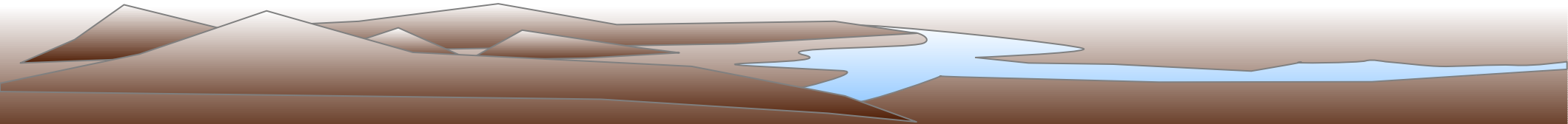


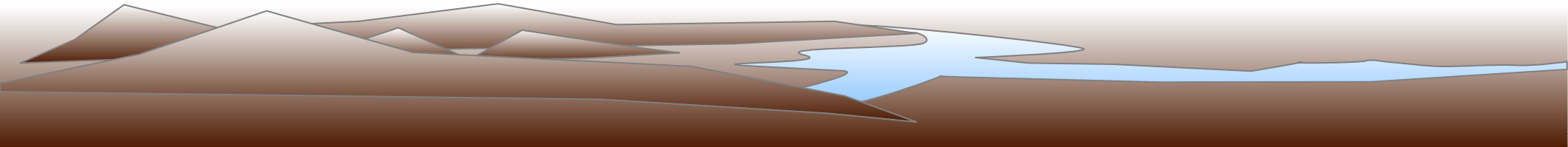
Conversion from Classical to Robotic Astronomy: The Lowell Observatory 0.8-m Telescope

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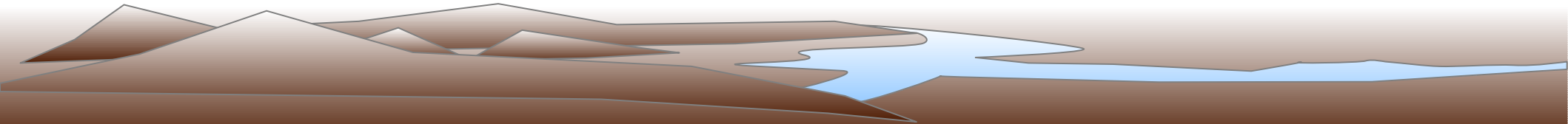
Philosophical Approach

- ☉ Robotic mode is a new option, not a conversion
- ☉ Observing with no oversight during the night
 - ☉ No image display
 - ☉ Log files are only source of feedback
- ☉ Foundation of system is an automaton
- ☉ Modular and layered design
- ☉ Linux/Solaris platform
- ☉ No off-site network connectivity required



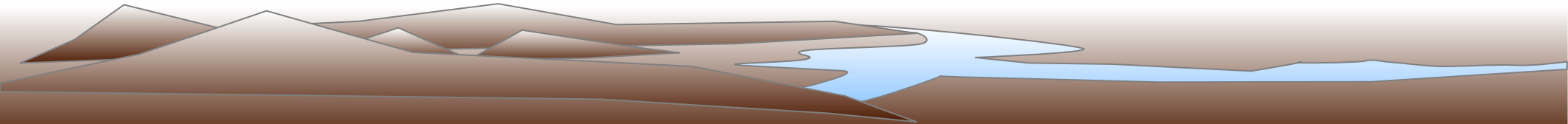
Ground Rules and Other Constraints

- ☉ Zero impact allowed on classical observing
- ☉ Continue to support instrument changes
- ☉ Essentially no funding or institutional support
- ☉ Do no harm to people or equipment
- ☉ Minimal effort required for operational support



System Overview

- ☉ One process per system
 - ☉ move – telescope interface layer
 - ☉ roboccd – camera operation
 - ☉ cmdr – observing queue
- ☉ Communication via IPC messages
 - ☉ Fast and tight communication
 - ☉ Simple program design
- ☉ Everything is modular and separate






Telescope





- ☉ 0.8-m aperture, Anderson Mesa Station
- ☉ English-yoke equatorial mount
 - ☉ 60°N pointing limit, very stable
- ☉ Closed-tube made of aluminum
 - ☉ Very strong temperature/focus relationship
- ☉ Digital stepper motors, RA/DEC and focus
- ☉ Ash dome
 - ☉ upper/lower shutter with narrow power pad
 - ☉ Bar code reader for absolute position knowledge

Camera(s)

PCCD (2001-2005)

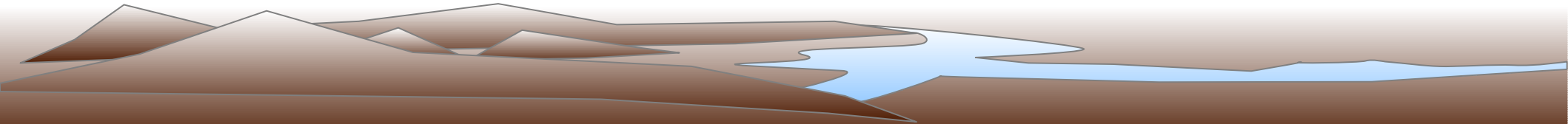
-  Photometrics TH7883 CCD (384x576), 1.3"/pix
-  Thermoelectrically cooled: -43°C
-  10-position filter wheel

NASAcam (2007-present)

-  EEV 2k CCD, 0.45"/pixel
-  Leach Gen3 readout electronics
-  Cryotiger cooling: -112°C
-  Two 10-position filter wheels

Environmental Data

- ☉ Davis weather station with server/logger
- ☉ Color day-time webcam (90° FOV)
- ☉ B/W high-sensitivity night camera (90° FOV)
- ☉ Dome CCTV monitoring camera
- ☉ Boresight high-sensitivity camera (10x14° FOV)
- ☉ Tube, mirror, and dome air temperature

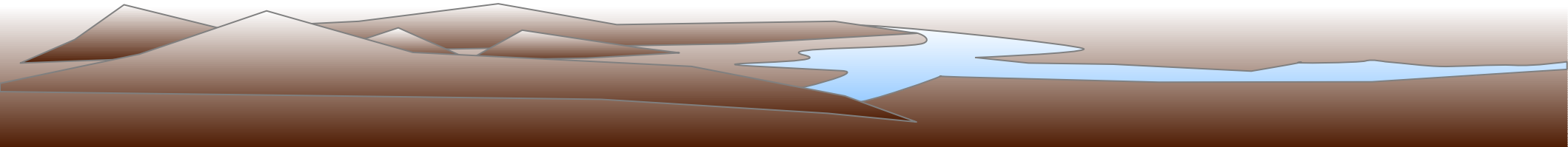


Interesting Lessons Learned

- ☉ How much real-time analysis?
 - ☉ Peak pixel: x, y, DN, FWHM, aperture flux
 - ☉ Sky background: mean, standard deviation
- ☉ How to focus?
 - ☉ Focus sweep, 1 second exposures work
 - ☉ No fitting, find best figure-of-merit (peak/flux)
- ☉ Timing control – LST is your friend
- ☉ No automated error recovery
 - ☉ Supervised recovery, only one failure allowed

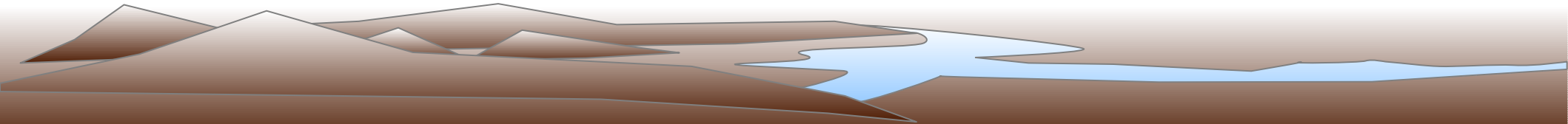
Interesting Lessons Learned, cont'd

- ☕ Good log files are critically important
 - ☕ Balance required between too much and too little
 - ☕ Use good search string markers for use with grep
 - ☕ Time-tag *everything*
 - ☕ *All* machines involved need good time, use ntp
- ☕ Standard star scheduling
 - ☕ Magic time when standard field at $X=2.5$
 - ☕ Work science data around standards



Interesting Lessons Learned, cont'd

- ☉ Demand for this system was limited at Lowell
 - ☉ Inertia, mysterious but consistent with most professional observatories
 - ☉ Non full-time mode excluded some projects
- ☉ Maintenance (non-observing) costs independent of classical/robotic usage



Come see the poster for more details

